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# Flexible Porous Carbon Black–Polymer Composites with a High Gauge Factor

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In this work, new conductive polymer films suitable for microfabrication have been developed. The solutions used are prepared by dispersing highly conductive nanoporous carbon blacks (n-CBs) in PHOTONEECE<sup>®</sup> (CBPh), polyvinyl alcohol (CBsPV), or gelatin (CBsGel). Conductive polymer composite thin films are formed by spin-coating on a clean glass substrate. The electrical conductivity and its response to strain are evaluated by a four-point bending method, which shows high gauge factors (GFs) of 150 and 523 for PVA- and gelatin-based composite films, respectively, in a low strain region. This clearly reveals the high potential capability of these novel nanocomposite films with the reported CB composite polymer showing a GF of ~100. It is considered that the porous structure of the n-CBs provides high sensitivity of flexible sensing elements that can be implemented into microfabrication processes easily.

# 1. Introduction

Recently, research studies on microdevices for strain and pressure sensing have been extensively performed because of various potential applications,<sup>(1–3)</sup> including reliable, flexible, and sensitive strain and pressure sensors for upcoming robotic and IoT applications.<sup>(4–7)</sup> For flexible device applications, flexible materials sensitive to strain are one of the key technologies. Among strain sensors, semiconductors,<sup>(8,9)</sup> ceramics,<sup>(10)</sup> and metals<sup>(11)</sup> are often used; nevertheless, these materials are basically not flexible. Conductive polymer composites made of nonconductive polymer and conductive filler are potential candidates of flexible strain-sensitive sensing materials suitable for the microfabrication of soft strain and pressure sensors.<sup>(12,13)</sup> Carbon black (CB) with a zero-dimensional feature is one of the carbon allotropes and is often used as a conductive filler for polymer composites.<sup>(14,15)</sup> Carbon-based materials including carbon nanotubes and graphene have been used for improving mechanical, electrical, and thermal properties.<sup>(16–18)</sup> CB has the advantage over graphene and carbon nanotubes in terms of cost and accessibility; however, the gauge factors (GFs) of CB-based composites in strain sensing are mostly lower than 100.<sup>(19,20)</sup> Therefore, a high-GF material based on the CB

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filler is desired for low-cost, accessible, and high-performance strain sensors. In this study, a highly conductive nanoporous CB with a smaller diameter than a conventional  $CB^{(21)}$  is chosen as the filler to improve GF. In this work, highly conductive nanoporous carbon black composite specimens with three types of matrix are synthesized and their GFs are evaluated.

### 2. Materials and Methods

#### 2.1 Conductive polymer for strain sensitivity evaluation

The percolation effect determines the conductivity of a conductive polymer, which is the crucial point in strain sensing. A schematic structure of the CB polymer composite for the evaluation of the percolation threshold<sup>(22)</sup> is shown in Fig. 1. The nanoporous CB particles (CB from Lion Specialty Chemicals; mean particle diameter, 34 nm) in solid-state powders or in a nanoparticle solution are mixed with the polymer. As the concentration of CB increases, the resistivity of the CB/composite decreases abruptly after reaching the percolation threshold, at which the highest sensitivity is expected in strain sensing.<sup>(23,24)</sup> A schematic of the test specimen is shown in Fig. 2. Porous CB particles are used as fillers, and three types of polymer are examined as the base matrixes of the composites, i.e., PHOTONEECE (Toray<sup>®</sup>), polyvinyl



Fig. 1. (Color online) Schematic of percolation effect in conductive polymer.



Fig. 2. (Color online) Schematic of test specimens for strain sensitivity evaluation. (a) Original and (b) bending state.

alcohol (PVA), and gelatin. PHOTONEECE is mixed with a solid-state CB powder owing to its lack of affinity with water, while PVA and gelatin are common polymers, which are miscible in water and water-based CB solutions. The deformation of the CB polymer composites changes the distance between CB particles, which in turn changes the electrical conductivity.<sup>(25)</sup> However, if the CB particles cannot be dispersed very well owing to aggregation, the strain sensitivity will decrease.

#### 2.2 Fabrication process of test specimen

The premixing processes of the conductive polymer composites are shown in Fig. 3. N-Methyl-2-pyrrolidone (NMP) is mixed with PHOTONEECE using a planetary centrifugal mixer for 10 min, as shown in Figs. 3(a1) and 3(a2). Then, the CB powder is mixed with the PHOTONEECE solution [Fig. 3(a3)] using the planetary centrifugal mixer again for 10 min.

For the premixing process of CBsPV, a PVA powder is poured into 95 °C hot water with stirring until the PVA powder is completely dissolved, as shown in Figs. 3(b1) and 3(b2). The CB water solution is then mixed with the PVA solution [Fig. 3(b3)] using the planetary centrifugal mixer for 10 min.

For the premixing process of CBsGel, a gelatin powder is added to 65 °C warm water with stirring at 800 rpm for 20 min, as shown in Fig. 3(c1). Glycerol is also added to gelatin [Fig. 3(c1)] to plasticize the gelatin. Then, the above solutions [Fig. 3(c2)] are mixed by rotating them for 10 min [Fig. 3(c3)]. Next, the CB solution is mixed with the gelatin solution.



Fig. 3. (Color online) Premixing processes of the CB polymer nanocomposite films.

Then, ultrasonication (60 min), mixing (10 min), and vacuum pumping (60 min) are performed to obtain a well-dispersed CB composite polymer. Finally, the dispersed CB composite polymer is spin-coated onto a 0.21 mm thick glass substrate at a rate of 2000 rpm for 25 s to obtain a conductive polymer thin film.

#### 2.3 Experimental setup for evaluation of strain sensitivity to resistance

To evaluate the intrinsic resistivity of the samples, the sheet resistance of the CB polymer composite thin films on the glass substrate is measured five times for each sample using a four-point probe tester (K-705RS Kyowariken<sup>®</sup>). Through measuring the different concentrations of CB polymer composite thin films using the four-point probe tester, we can determine the relationship of sample sheet resistance with increasing concentration. The film thickness is measured four times for each sample from the film height using a surface profiler (P-10 Tencor<sup>®</sup>). The average thicknesses of CBPh-, CBsPV-, and CBsGel-based composite films are approximately  $1600 \pm 300$ ,  $2500 \pm 600$ , and  $800 \pm 100$  nm, respectively. In addition, the resistivity  $\rho$  can be obtained as

$$\rho = R_s t, \tag{1}$$

where  $R_s$  is the sheet resistance and t is the thickness. The homemade experimental setup for strain sensitivity evaluation using a four-point bending measurement setup is shown in Fig. 4. The sample is electrically connected to an I-V measurement system. While the sample is set on a four-point bending system with the upper load and bottom support bars, force is applied to the sample at four contact points to produce the strain calculated from the applied force. I-V is measured under various force applications to evaluate the resistance variation caused by strain. In I-V measurement, a voltage of 0.1 V is applied to the sample from -5 V to 5 V and back and forth. The I-V of each sample is measured three times at a specific strain. The resistance of the samples is evaluated from the average reciprocal of the slope of I-V measurement results.



Fig. 4. (Color online) Schematic of strain sensitivity evaluation setup using four-point bending setup.

#### 3. **Results and Discussion**

#### Formation of CB polymer composite films 3.1

From the optical micrographs of the prepared films shown in Fig. 5, the aggregated CB particles are recognized as black spots in the PHOTONEECE matrix. This means that CB particles are not dispersed well. The aggregation of the CB particles in the matrix possibly causes low sensitivity to strain. As shown in Figs. 5(b) and 5(c), the CB particles are well dispersed in the PVA and gelatin matrixes. SEM images of the CB morphology of the CB polymer/composite are shown in Fig. 6. The CB particles on CBPh [Fig. 6(a)] aggregate, which indicates the inadequate dispersion of the CB particles. In addition, Fig. 6(b) reveals that the extent of CB aggregation is lower than that of CBPh aggregation, whereas Fig. 6(c) indicates that the extent of aggregation of the CB particles in gelatin is lower than that of other materials. Because of the superior miscibility of the CB solution in the water-based polymer solution, the CB particles are dispersed well in the polymer.



(a)

Fig. 5. (Color online) Micrographs of samples: (a) CBPh-2.28 wt% CB, (b) CBsPV-1.60 wt% CB, and (c) CBsGel-1.94 wt% CB.



Fig. 6. (Color online) SEM images of morphology of CB on composites (a) CBPh-2.28 wt% CB, (b) CBsPV-1.60 wt% CB, and (c) CBsGel-1.94 wt% CB.

#### 3.2 Resistivity of CB composites

The resistivity change of the CBPh composite film shows a logarithmic decrement with increasing CB concentration, as shown in Fig. 7. This reveals that the percolation thresholds of CBPh, CBsPV, and CBsGel are observed at approximately 2.3, 1.6, and 1.9 wt%, respectively. In the next subsection, the samples with a CB concentration at the percolation threshold are chosen to evaluate the strain sensitivity.

## 3.3 Temperature dependence of resistivity of CB polymer composites

The temperature dependence of the samples is investigated using a temperature-controlled oven with the experimental setup shown in Fig. 8. The variation in resistance is defined as

$$S_{temp} = \frac{\Delta R_t}{R_{t0}},\tag{2}$$

where  $\Delta R_t = R_t - R_{t0}$ , with  $R_t$  and  $R_{t0}$  being the resistance at a specific temperature and the resistance at room temperature (20 °C), respectively. The results indicate that CBsGel is the



Fig. 7. (Color online) CB concentration dependence of resistivity of composite films.



Fig. 8. (Color online) Relationship between sensitivity and temperature of (a) CBPh-2.28 wt% CB, (b) CBsPV-1.60 wt% CB, and (c) CBsGel-1.94 wt% CB.

most sensitive to the variation in temperature (-0.58 %/K) before reaching the environmental temperature of 60 °C. On the other hand, the variations in the resistances of CBsPV and CBPh are only -0.15 %/K and -0.09 %/K approximately before reaching the environmental temperature of 60 °C, which reveals that CBsPV and CBPh are less sensitive to temperature than CBsGel. In addition, the changes in the resistances of CBsPV (-0.15 %/K) and CBPh (-0.09 %/K) are less than those in other work on a CB composite polymer strain sensor<sup>(25)</sup> (-0.2 %/K). This clearly demonstrates the potential use of CBsPV and CBPh as strain sensing materials.

### 3.4 Strain sensitivity of CB composites

To estimate the strain sensitivity to the resistance of the thin films on the glass substrate, an Au electrode pattern is formed on the films by electron beam evaporation and photolithography, as shown in Fig. 9. Titanium (20 nm) is deposited on the CB polymer composite thin film as an adhesion layer, and a 180 nm gold layer is deposited on the titanium layer as the electrodes. In addition, the surface roughness of each sample is measured three times using a surface profiler (ET-200 Kosaka Laboratory<sup>®</sup>), and the arithmetical mean roughness (Ra) is obtained as the parameter of the surface roughness of the samples. The *Ra* values of CBPh, CBsPV, and CBsGel are  $0.006 \pm 0.001$ ,  $0.011 \pm 0.004$ , and  $0.007 \pm 0.004 \,\mu\text{m}$ , respectively. This reveals that the CB polymer composite thin films have a roughness with a dimension of 0.001  $\mu\text{m}$ , which is beneficial for contact with the Ti adhesion layer.

Force sensitivity is measured using the four-point bending setup, as described previously. Tensile stress is applied to the nanocomposite film and the resistance change  $\Delta R$  is evaluated. The resistance of the samples subjected to different forces is obtained by I-V measurement and typical results are shown in Fig. 10. Because of the good contact between the electrodes and the CB polymer composite thin film, the I-V curves are straight in a cycle test, which also indicates a good ohmic contact between the electrodes and the CB composite polymer thin film. Similarly, a good ohmic contact is observed at high strains, which shows that the electrodes are not peeled-off from the CB polymer composite thin film by the applied strain.



Fig. 9. (Color online) Photograph of test specimen.



Fig. 10. (Color online) I-V curve variation of CBsGel composite with various loads evaluated using four-point bending setup.



Fig. 11. (Color online) Strain dependence of sensitivity ( $\Delta R/R_0$ ) in composite films, CBPh-2.28 wt% CB (inset), CBsPV-1.60 wt % CB, and CBsGel-1.94 wt% CB.

The strain sensitivity of the samples to the resistance is defined as  $\Delta R/R_0$ . The results of the strain sensitivities of the CBPh films with various CB concentrations are shown in Fig. 11. It is observed that the sensitivity does not show a linear relationship in the measured strain region. However, a high sensitivity is observed in a limited region, Here, we discuss the highest sensitivity performance. The CBPh composite film exhibits the lowest sensitivity performance, and the strain sensitivities of CBsPV and CBsGel composite films are much higher than that of the CBPh composite. The reason is that the aggregation of the CB particles in PHOTONEECE reduces the strain sensitivity. On the other hand, the strain sensitivity performance measured using the two-probe sensing setup may degrade owing to the contact resistance between the electrodes and the CB polymer composite thin film.

Additionally, the CB particles in an aqueous solution are miscible in other water-based solutions. Thus, the CB particles can be well dispersed in the polymer, which enhances the strain sensitivity. On the other hand, the slight aggregation of the CB particles in PHOTONEECE causes the low sensitivity to strain. Because of the limited dispersion, the resistance of the CBPh film decreases with increasing applied force. Figure 12 shows the variation in the resistance of the CB polymer composite film under cyclic strain application.



Fig. 12. (Color online) Demonstration of force sensing in composite films (a) CBPh-2.28 wt% CB, (b) CBsPV-1.60 wt% CB, and (c) CBsGel-1.94 wt% CB.

Table 1			
Summarized results of the strain sensitivity.			
Sample	А	В	С
GF	-3.3	150	523
CB particles	Powder	Solution	Solution
Polymer	PHOTONEECE	PVA	Gelatin
Percolation threshold	~2.3 wt% CB	~1.6 wt% CB	~1.9 wt% CB

Force is applied to the upper load perpendicularly (On-state) and removed (Off-state) alternately to estimate the repeatability of measurements of the CB polymer/composite. The GFs of the samples are summarized in Table 1, clearly indicating that the CBsPV and CBsGel composite films show much higher GFs of 150 and 523, respectively, which are higher than those in other works regarding CB composites (GF < 100).<sup>(19,20)</sup> This reveals the high potential of applying CBs to low-cost, simple-process, and flexible strain sensors based on a flexible conductive polymer. Currently, the reason for the saturation in the sensitivity at the high-strain region is not clear; but basically, the percolation effect on the resistivity is a nonlinear phenomenon, which possibly affects the nonlinearity of sensitivity.

### 4. Conclusions

In this work, three types of CB polymer composite are synthesized by dispersing highly conductive porous nanostructured CB in PHOTONEECE, PVA, and gelatin. The CB particles can be dispersed well in PVA and gelatin. The CB concentration dependence on the resistivity shows a logarithmic linear relationship, also indicating the percolation effect of the CB particles in these polymers. Among the specimens, the CBsPV and CBsGel composite films at the percolation threshold exhibit the highest GFs of 150 and 523, respectively. These results show the potentially high capability of the CBsPV composite film as a strain and force sensing element with a simple process, low cost, and flexibility to detect a small strain or force.

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