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# Surface-acoustic-wave-based Ammonia Gas Sensors Using MoS<sub>2</sub>/SiO<sub>2</sub> Composites

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In this study, delay line surface acoustic wave devices were prepared using a  $128^{\circ}$  Y-cut LiNbO<sub>3</sub> piezoelectric substrate. Pure MoS<sub>2</sub> and composite materials of MoS<sub>2</sub> and SiO<sub>2</sub> with various morphologies were sprayed to form sensitive layers. By adjusting the amount of NH<sub>4</sub>OH catalyst in the precursors, the particle sizes of SiO<sub>2</sub> nanospheres were successfully controlled at 70, 200, and 300 nm by the sol-gel method. SiO<sub>2</sub> nanospheres were then added to the precursor for preparing rosette-shaped MoS<sub>2</sub>, and nanocomposites were synthesized by the hydrothermal method. As a result, two types of composite material were obtained, namely, the S–M structure and the M–S structure. As ammonia gas sensors, the results showed that all the sensors exhibited negative frequency shifts as the NH<sub>3</sub> gas concentration increased. Surface area and pore size distribution analyzer (BET) analysis showed that the highest specific surface area of 115.57 m<sup>2</sup>/g occurred on the S–M structural composite material. The sensor using the S–M structural composite material has a sensitivity of 1932 Hz/ppm to NH<sub>3</sub> gas. The sensing linearity R-squared value is approximately 0.99, with continuous dynamic sensing at NH<sub>3</sub> gas concentrations of 5–50 ppm. Finally, we revealed that decorating MoS<sub>2</sub> with SiO<sub>2</sub> nanospheres can improve the adsorption of ammonia molecules and significantly enhance sensitivity.

# 1. Introduction

Ammonia (NH<sub>3</sub>) comes primarily from industrial manufacturing processes. It can react with nitrogen oxides (NO<sub>X</sub>), sulfur oxides (SO<sub>X</sub>), and water molecules (H<sub>2</sub>O) in air to form ammonium salts. It is the main source of the major pollutants and PM<sub>2.5</sub> in haze.<sup>(1)</sup> The U.S. Occupational Safety and Health Administration (OSHA) has declared that the average ammonia exposure limits for human workplaces are 35 ppm for 15 min and 25 ppm for 8 h.<sup>(2)</sup> If a human inhales violently high concentrations of NH<sub>3</sub>, it will cause tears, coughing, difficulty in breathing and other symptoms, and even death.<sup>(3)</sup> In addition, in the biomedical field, the ammonia concentration in human exhalation is used to determine the possibility of kidney

disease. The ammonia concentration in the breath of healthy people is about 960 ppb, while it is about 4880 ppb in the breath of patients with kidney disease.<sup>(4,5)</sup>

At present, semiconductor oxides are mostly used as gas sensors. They have the advantages of low cost and simple operation, but there are still some shortcomings that need to be improved. For example, high operating temperatures are required to achieve excellent performance,<sup>(6,7)</sup> which will lead to high power consumption, hindering wide application and integration in the Internet of Things.<sup>(8)</sup> Therefore, it is highly beneficial to study high-performance gas sensors that can operate at room temperature and continuously monitor harsh conditions and environments. In this study, we use a delay line surface acoustic wave (SAW) device as the main structure of our ammonia sensor, and rosette spherical molybdenum disulfide (MoS<sub>2</sub>) and molybdenum disulfide/silicon dioxide (MoS<sub>2</sub>/SiO<sub>2</sub>) composite materials are used for sensing layers. SAW devices can be used in gas sensors to measure trace concentrations with high sensitivity and fast response at room temperature.<sup>(9)</sup> In addition, the electrical signal generated by the SAW device can support wireless sensing and has excellent electrical signal.<sup>(10)</sup>

SAW devices are mainly composed of two sets of interdigital transducers (IDTs). By applying electrical signals to the input IDTs, the acoustic waves will be generated through the inverse piezoelectric effect and propagate through the delay line area on the surface of the device. At the output IDTs, the acoustic waves will be converted into electrical signals through the positive piezoelectric effect. During the transmission process of the SAW device, the delay line area is coated with nanomaterial to form a sensitive layer that adsorbs gas molecules, causing physical changes and thereby changing the center frequency of the SAW sensor.<sup>(11)</sup>

 $MoS_2$  has a layered crystal structure in which molybdenum atoms and sulfur atoms are covalently bonded to form a single-layer structure of molybdenum disulfide planes, and each layer of molybdenum disulfide is connected by van der Waals forces. The layered structure has a high specific surface area and will have a high sensitivity and selectivity when used as a gas sensor.<sup>(12,13)</sup> In our previous research,  $MoS_2$  was found to be an excellent gas-sensitive material for ammonia sensors. Moreover, it was also learned that the surface morphology had a considerable effect on the adsorption of ammonia molecules.<sup>(14)</sup> In this study, we modified  $MoS_2$ with  $SiO_2$  to explore the gas-sensing properties of ammonia. The hydrothermal method was used to combine  $MoS_2$  and  $SiO_2$  into composite materials with the M–S structure ( $SiO_2$  nanospheres completely covered by  $MoS_2$ ) and the S–M structure ( $SiO_2$  nanospheres distributed around the  $MoS_2$  rosette). Ammonia sensors were constructed with three different sensing materials including  $MoS_2$  and its composite materials ( $MoS_2/SiO_2$  and  $SiO_2/MoS_2$ ), and their sensing characteristics for ammonia were compared.

# 2. Materials and Methods

# 2.1 Preparation of silicon dioxide nanospheres

In this study, we used the sol-gel method to prepare the silicon dioxide nanospheres. Tetraethoxysilane [TEOS; Si( $OC_2H_5$ )\_4] was used as the precursor and ammonia water ( $NH_4OH$ ) as the catalyst to synthesize silicon dioxide nanospheres through hydrolysis and condensation. In

the experiment, the concentrations of deionized (DI) water (1 mL), ethanol ( $C_2H_5OH$ , 100 mL), and TEOS (10 mL) were fixed, and that of  $NH_4OH$  was varied as 5, 10, and 15 ml to prepare various morphologies of SiO<sub>2</sub> nanospheres.

First, NH<sub>4</sub>OH, DI water, and ethanol were mixed and magnetically stirred at 600 rpm for 10 min, and then TEOS was added to complete the preparation of SiO<sub>2</sub> precursor solutions. Next, SiO<sub>2</sub> precursor solutions were kept at 60 °C for 4 h. After cooling to room temperature, the reactant was transferred into a centrifuge tube using a dropper, centrifuged at 10000 rpm for 10 min using a centrifuge, and washed with ethanol and DI water for 3 cycles. To remove by-products and impurities, the centrifuged product was placed in a petri dish and baked at 80 °C for 8 h. After the water vapor was removed, the preparation of SiO<sub>2</sub> nanospheres was completed. The preparation process is shown in Fig. 1.

# 2.2 Preparation of composite materials of MoS<sub>2</sub> and SiO<sub>2</sub> nanospheres

To prepare the composites of  $MoS_2$  and  $SiO_2$  nanospheres,  $SiO_2$  nanospheres with the various morphologies described above were coated in advance with sodium dodecyl benzene sulfonate (SDBS), used as the surfactant, in DI water. Then, sodium molybdate dihydrate ( $Na_2MoO_4$ ·2H<sub>2</sub>O) used as the molybdenum source and thioacetamide ( $C_2H_5NS$ ) used as the sulfide source were added into the solution. Finally, hydrochloric acid (HCl) was added to adjust the pH of the precursors. The precursor solution underwent a composite reaction under high temperature and pressure by the hydrothermal method to form  $MoS_2/SiO_2$  composite materials.



Fig. 1. (Color online) Preparation of SiO<sub>2</sub> nanospheres by sol-gel method.

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The preparation of composite materials is shown in Fig. 2. The obtained 70 nm or 300 nm  $SiO_2$  nanospheres (0.05 g) and SDBS (0.05 g) were mixed with DI water (40 mL), magnetically stirred at 600 rpm for 1 h, and then Na<sub>2</sub>MoO<sub>4</sub>·2H<sub>2</sub>O (0.05 M) and C<sub>2</sub>H<sub>5</sub>NS (0.15 M) were added. Next, the solution was adjusted to pH 5 with HCl and magnetically stirred at 600 rpm for 1 h to complete the preparation of MoS<sub>2</sub> /SiO<sub>2</sub> composite precursor solutions. Then the precursor solution was poured into a 50 mL Teflon liner, placed in an autoclave, and sealed tightly. The hydrothermal reaction was carried out at 180 °C for 20 h. After cooling to room temperature, the reactants were poured into a centrifuge tube with a dropper, centrifuged at 10000 rpm for 10 min, and washed with ethanol and DI water for three cycles to remove by-products and impurities in the powder. Finally, the centrifuged product was placed in a petri dish and baked at 80 °C for 8 h. After water vapor was removed, the preparation of the MoS<sub>2</sub>/SiO<sub>2</sub> composite materials was complete.

## 2.3 Fabrication of SAW devices

In this study, we used 128° Y-cut lithium niobate as the piezoelectric substrate of the SAW device. The IDT electrodes using aluminum metal (Al/Ti) were sputtered on the substrate using lithography technology. The thickness of the Ti metal used as an adhesion layer was 20 nm, and the thickness of the Al electrode was 100 nm. The designed parameters were a linewidth (*d*) of 8  $\mu$ m, wavelength ( $\lambda$ ) of 32  $\mu$ m, 30 pairs of IDTs, overlap length (*W*) of 2.7 mm, distance (*L*) of the delay line area between input and output IDTs of 3 mm, and reflective grating of 30 pairs. The acoustic velocity of LiNbO<sub>3</sub> was about 3992 m/s, which resulted in a resonance frequency of about 125 MHz for the SAW device. The component schematic is shown in Fig. 3.



Fig. 2. (Color online) Preparation of  $MoS_2/SiO_2$  composite materials by hydrothermal method.



Fig. 3. (Color online) Schematic of mask design for SAW devices.

## 2.4 Fabrication of SAW gas sensing devices

The preparation of a SAW gas sensor is shown in Fig. 4. The sensing material of  $MoS_2$  or  $MoS_2/SiO_2$  composite was fully mixed with ethanol in a weight ratio of 1:30, then the suspension was coated by spray onto the patterned delay line area through an atomizer and dried on a heating platform at 80 °C to complete the preparation of the SAW gas sensors.

Figure 5 shows the schematic of the gas sensing system. First, the gas sensing chamber and mixing chamber were pumped to a rough vacuum, then the nitrogen gas was introduced through the bubbler at a fixed flow rate to carry ammonia vapor into the mixing chamber for mixing. The Antoine equation was used to estimate the ammonia concentration.<sup>(15,16)</sup> After reaching the required gas concentration, the valve between the ammonia bubbler and the mixing chamber was closed to stop the supply of ammonia, and the valve between the mixing chamber and the sensing chamber was opened to allow gas exchange between these two chambers.

Finally, after the system reached a steady state, the frequency response of the SAW gas sensor was measured in the sensing chamber by a network analyzer. After measurement, the air extraction pump was turned on to extract the residual air inside the chamber, and nitrogen gas was introduced to clean the chamber and repeat the other measurements.

# 3. Results and Discussion

### 3.1 Characteristics of the designed SAW device

The frequency response of the completed SAW device was measured with a network analyzer in air at room temperature. The measured center frequency of the component without coating of the sensing layer was approximately 123 MHz with a return loss ( $S_{11}$ ) of -13 dB and an insertion loss ( $S_{21}$ ) of -14 dB, as shown in Fig. 6.



Fig. 4. (Color online) Preparation of a SAW gas sensor.



Fig. 5. (Color online) Schematic of the gas sensing system.



Fig. 6. S parameters of the SAW device: (a)  $S_{11}$  and (b)  $S_{21}$ .

# 3.2 Characteristic analysis of silicon dioxide

It was found that the contents of  $NH_4OH$  in the precursors will affect the particle sizes of  $SiO_2$  nanospheres. As ethanol of 100 mL and TEOS of 10 mL were fixed in the precursors, the morphologies of the obtained  $SiO_2$  with various amounts of  $NH_4OH$  catalyst are shown in Fig. 7. The particle sizes of the  $SiO_2$  nanospheres prepared with  $NH_4OH$  of 5, 10, and 15 mL were 70, 200, and 300 nm, respectively.

The EDS elemental analysis showed that the atomic ratio of oxygen to silicon was close to 2:1 for the three morphologies of SiO<sub>2</sub>. The XRD diffraction patterns indicated that the three morphologies of SiO<sub>2</sub> nanospheres had only wide diffractions and behaved as amorphous forms, as shown in Fig. 8, similarly to those described in the literature.<sup>(17)</sup> In addition, the TEM analysis for SiO<sub>2</sub> nanospheres of 70 nm size also revealed that the SiO<sub>2</sub> nanospheres synthesized by the sol-gel method were amorphous, as shown in Fig. 9.



Fig. 7. (Color online) Morphologies of  $SiO_2$  nanospheres prepared with various amounts of  $NH_4OH$ : (a) 5, (b) 10, and (c) 15 mL.



Fig. 8. (Color online) XRD diffraction patterns of SiO<sub>2</sub>.



Fig. 9. (Color online) TEM analysis of  $SiO_2$  nanospheres with particle size of 70 nm: (a) HRTEM image and (b) diffraction pattern.

## 3.3 Characteristic analysis of molybdenum disulfide and composite materials

To prepare pure  $MoS_2$  nanospheres,  $Na_2MoO_4$  (0.05 M) and  $C_2H_5NS$  (0.15 M) were used as the molybdenum and sulfur sources, respectively, and the precursor was adjusted to a pH of 5 using HCl. By referring to our previous report,<sup>(14)</sup> the MoS<sub>2</sub> with rose morphology was obtained using the hydrothermal method, as shown in Fig. 10(a).

The composite materials using  $MoS_2$  nanospheres and  $SiO_2$  nanospheres with particle sizes of 70 and 300 nm, respectively, were obtained, as described above. The SEM surface morphologies revealed that the composite material synthesized with  $SiO_2$  nanospheres with a particle size of 300 nm showed that the  $SiO_2$  nanospheres were completely covered by  $MoS_2$ , as shown in Fig. 10(b); this will be referred as the M–S structure. On the other hand, the composite material synthesized with  $SiO_2$  nanospheres with a particle size of 70 nm showed that the  $SiO_2$ nanospheres were distributed around the  $MoS_2$  rosette morphology, as shown in Fig. 10(c); this will be referred as the S–M structure.

The crystalline structure of pure  $MoS_2$  nanospheres was analyzed by TEM, as shown in Fig. 11. Figure 11(b) shows the area selected for further HRTEM analysis, from which it was found that the  $MoS_2$  nanospheres were in sheet form, stacked with the lattice spacing of about 0.65 nm, which is consistent with the literature<sup>(18)</sup> and corresponds to the (002) crystal plane of the  $MoS_2$  hexagonal crystal system. In addition, Fig. 11(c) shows the diffraction patterns resulting from the  $MoS_2$  fast Fourier transform (FFT) mode [region shown in Fig. 11(b)], from which it can be confirmed that the polycrystalline  $MoS_2$  nanospheres prepared by the hydrothermal method were composed of many nanosheets.

Figures 12 and 13 show the EDS mappings of the elemental analysis of composite materials for the M–S and S–M structures, respectively. Figure 12 shows that the composite material with the M–S structure was composed of Mo, S, Si, and O, and the SiO<sub>2</sub> nanospheres were wrapped in MoS<sub>2</sub> nanospheres. On the other hand, Fig. 13 shows that the S–M structure was also composed of Mo, S, Si, and O, but the SiO<sub>2</sub> nanospheres were distributed around the periphery of MoS<sub>2</sub> nanospheres. Through the EDS mapping analysis, the composition and distribution of elements can be more clearly confirmed.



Fig. 10. (Color online) SEM surface morphologies of the sensing materials: (a) pure  $MoS_2$ , (b) composite material with M–S structure, and (c) composite material with S–M structure.



Fig. 11. (Color online) TEM images of  $MoS_2$  nanospheres: (a) low-magnification TEM image, (b) HRTEM image, and (c) FFT diffraction patterns.



Fig. 12. (Color online) EDS mappings of elemental analysis for composite material with M-S structure.



Fig. 13. (Color online) EDS mappings of elemental analysis for composite material with S-M structure.

Figure 14 shows the XRD patterns of  $MoS_2$  and  $SiO_2/MoS_2$  nanocomposite materials. The XRD peaks at  $2\theta = 14.2$ , 32.8, 39.6, and 58.5° were indexed to be the (002), (100), (101), and (112) planes of the  $MoS_2$  nanospheres with a tetragonal structure. It was revealed that both M–S and S–M structures of composite materials exhibit  $MoS_2$  and  $SiO_2$  diffraction peaks. In addition, in the X-ray diffraction analysis of the S–M structure, it was found that, except for the (002) main crystalline phase of  $MoS_2$ , other crystalline phases were affected by the decorated  $SiO_2$  nanospheres on the surfaces of  $MoS_2$ , and the diffraction intensity was weak compared with those of pure  $MoS_2$  and M-S structures.

Figure 15 shows the BET analysis results of  $MoS_2$  and composite materials with M–S and S–M structures. From the adsorption and desorption characteristic curves, the specific surface areas can be calculated to be 30.48, 32.59, and 115.57 m<sup>2</sup>/g for pure  $MoS_2$ , the M–S structure, and the S–M structure, respectively. The results indicated that the composite material with the S–M structure had a much higher specific surface area and optimal adsorption and desorption characteristics.

#### 3.4 Analysis of ammonia gas sensor

The SAW gas sensors sprayed with  $MoS_2$  and composite materials with the M–S and S–M structures on the delay line areas were denoted as Sensor-A, Sensor-B, and Sensor-C, respectively. The frequency responses at different ammonia concentrations for the three sensors are shown in Figs. 16–18, respectively.

The resonance center frequency of all sensors with sensing materials coated and without  $NH_3$  gas was approximately 122 MHz. As the  $NH_3$  gas concentration increased, the sensors shifted to lower frequencies. The frequency shifts of the three gas sensors with  $NH_3$  gas concentration are shown in Fig. 19. The sensitivity can be calculated as follows.



Fig. 14. (Color online) XRD diffractions of  $MoS_2$  and  $SiO_2/MoS_2$  composite materials.



Fig. 15. (Color online) BET analysis results of  $MoS_2$  and composite materials with M–S and S–M structures: (a) pure  $MoS_2$ , (b) composite material with M–S structure, and (c) composite material with S–M structure.



Fig. 16. (Color online) (a) Frequency variations of Sensor-A at different ammonia concentrations. (b) Enlargement around the center frequency of 122 MHz.



Fig. 17. (Color online) (a) Frequency variations of Sensor-B at different ammonia concentrations. (b) Enlargement around the center frequency of 122 MHz.



Fig. 18. (Color online) (a) Frequency variations of Sensor-C at different ammonia concentrations. (b) Enlargement around the center frequency of 122 MHz.



Fig. 19. (Color online) Frequency shifts of sensors with NH<sub>3</sub> gas concentration: (a) Sensor-A, (b) Sensor-B, and (c) Sensor-C.

$$S(\text{Hz/ppm}) = \frac{\left|f_{air} - f_{gas}\right|}{\Delta c} \tag{1}$$

Here, S is the sensitivity with the unit of Hz/ppm,  $f_{air}$  is the frequency of the sensor in air,  $f_{gas}$  is the frequency at which ammonia gas is detected, and  $\Delta C$  is the change in gas concentration. According to Eq. (1), the sensitivities of Sensor-A, Sensor-B, and Sensor-C were calculated to be 1643, 1849, and 1932 Hz/ppm, respectively.

In a SAW gas sensor, the center frequency shift  $(\Delta f)$  may be related to elastic or acousticelectrical interactions of the sensing material or to the mass load changes due to the adsorption of gas molecules.<sup>(19)</sup> However, the elastic change of the sensing material will cause the center frequency to move to the higher end (the material becomes stiffer, which will increase the center frequency). That is, the material elasticity can be ruled out and its effects ignored<sup>(20)</sup> because the frequency shifts to the lower end in this experiment.

The acoustic and electrical effects on the gas sensor can be expressed using the following formula.<sup>(20)</sup>

$$\Delta f = -f_0 \times \frac{k^2}{2} \times \left(\frac{1}{1 + \left(\frac{V_0 C_s}{\sigma_s}\right)^2}\right)$$
(2)

 $f_0$  is the unperturbed center frequency of the sensor,  $V_0$  is the unperturbed SAW velocity of about 3992 m/s of the SAW device on an LiNbO<sub>3</sub> substrate,  $\sigma_s$  is the conductivity of the sensing layer,  $f_0$  is the center frequency of the sensor,  $k^2$  is the electromechanical coupling coefficient, and  $C_s$  is the unit length capacitance of the SAW device. Since MoS<sub>2</sub> is an *n*-type semiconductor, as it is exposed to ammonia gas, the number of electrons in the conduction band of MoS<sub>2</sub> will increase<sup>(21)</sup> owing to the electron-donating characteristics of ammonia molecules,<sup>(22)</sup> and the conductivity of the material increases,<sup>(19)</sup> which will result in an electrical load effect and cause the center frequency of the device to shift to the lower end.

Furthermore, it must be noted that mass loading will cause the center frequency to shift toward the lower end (i.e., lower the center frequency). From the results obtained, it can be concluded that the frequency shift is mainly due to the mass loading effect. The surface of silicon dioxide (SiO<sub>2</sub>) contains a rich amount of hydroxyl groups (–OH) because, when it encounters water molecules, a chemical reaction occurs that produces hydroxyl groups.<sup>(23)</sup> Since SiO<sub>2</sub> is rich in hydroxyl groups (–OH), the N atoms or H atoms in NH<sub>3</sub> can form hydrogen bonds with the (–OH) groups in SiO<sub>2</sub>. Moreover, so SiO<sub>2</sub> has a strong water absorption capacity, which is beneficial to highly water-soluble NH<sub>3</sub> sensing.

The mass loading effect of the gas sensor can be expressed as follows.<sup>(24,25)</sup>

$$\Delta f = (k_1 + k_2) \times f_0^2 \times \Delta \rho s \tag{3}$$

Here,  $k_1$  (-3.775 × 10<sup>-8</sup> m<sup>2</sup> s kg<sup>-1</sup>) and  $k_2$  (-1.73 × 10<sup>-8</sup> m<sup>2</sup> s kg<sup>-1</sup>) are the material constants of the 128° Y-cut LiNbO<sub>3</sub> substrate. Note here that  $k_1$  and  $k_2$  are both negative values, so a positive change in  $\Delta \rho s$  will lead to a negative value of  $\Delta f$ , resulting in a shift of the center frequency to a lower frequency.<sup>(26,27)</sup>

In this study, Sensor-C, with an S–M structured composite material as the sensing layer, showed the best performance as an ammonia sensor. The reason may be that  $MoS_2$  has a nanoflower shape with a high specific surface area decorated with SiO<sub>2</sub> nanospheres with hydroxyl-rich characteristics and high specific surface area, which will provide many more active sites to adsorb ammonia molecules and obtain higher sensing performance<sup>(28,29)</sup> than other sensors.

The selectivity of gas sensing for the three gas sensors was analyzed for sensing acetone, ethanol, and toluene gases. The sensing temperatures were all room temperature, and the concentration of each gas was 50 ppm. The results are shown in Fig. 20. From the results, it can be seen that all the sensors exhibited good selectivity. However, Sensor-C had a lower selectivity than Sensor-A and Sensor-B, although it exhibited the best sensing performance. The reason may be that the (-OH) hydroxyl group in SiO<sub>2</sub> forms hydrogen bonds not only with NH<sub>3</sub>, but



Fig. 20. (Color online) Sensing selectivities of the three gas sensors to different gases.

also with acetone and alcohol. Compared with Sensor-A and Sensor-B, the response of Sensor-C to acetone and alcohol was higher.

Finally, three sets of gas sensing devices were used to determine their dynamic gas sensing characteristics at room temperature with an ammonia concentration of 50 ppm. The phase variations of the center frequency were observed, and the response time and recovery time were determined using a network analyzer (P9372A Keysight streamline USB Vector Network). During the measurement, ammonia gas with a concentration of 50 ppm was first introduced into the sensing chamber and then the phase shift of the center frequency was recorded. After the phase shift stabilized, the ammonia gas in the cavity was pumped out, and the phase angle of the center frequency returned to its initial state. As the phase angle decreased and rose by 90%, durations were recorded as the response time and recovery time, respectively.

Figure 21 shows the results of the three sensors. The response times were found to be 32, 30, and 21 s, whereas the recovery times were 32, 30, and 23 s for Sensor-A, Sensor-B, and Sensor-C. Phase can be converted to frequency according to Eqs. (4) and (5).

$$\frac{\left|\theta_{air} - \theta_{gas}\right|}{\theta_{air}} \times 100\% = \Delta\theta \tag{4}$$

$$f_{air} \times \Delta \theta = \Delta f \tag{5}$$

Here,  $\theta_{air}$  is the phase angle of the center frequency in air,  $\theta_{gas}$  is the phase angle of the center frequency in an atmosphere with 50 ppm ammonia,  $\Delta\theta$  is the percentage of phase angle displacement, and  $\Delta f$  is the frequency displacement. The change in phase angle can be converted into a change in frequency through the above formulas (see Table 1). The values of  $\Delta f$  in Table 1 were close to those obtained in Fig. 19. Sensor-C was used to perform continuous dynamic sensing with ammonia gas at concentrations of 5–50 ppm. As shown in Fig. 22, the results exhibit an excellent sensing linearity with an R-squared value of about 0.99167.

Finally, compared with other works in the literature, the ammonia gas sensor we prepared in this study showed excellent sensitivity, response time, and recovery time,<sup>(30–34)</sup> as shown in Table 2.



Fig. 21. (Color online) Dynamic response characteristics of each sensor: (a) Sensor-A, (b) Sensor-B, and (c) Sensor-C.

Table 1

Phase angle displacement and converted frequency shift of three gas sensors at 50 ppm ammonia gas.

Sensor number	$\theta_{air}$ (°)	$\theta_{gas}$ (°)	$f_{air}$ (Hz)	$\Delta f(\text{kHz})$
A	135.5678	135.6616	122.941326	85.064
В	135.4949	135.6013	122.652542	96.315
С	135.4979	135.6098	122.597988	101.246



Fig. 22. (Color online) Dynamic response of Sensor-C to NH<sub>3</sub> gas of 5–50 ppm.

SAw annonia sensor performance.							
Working Frequency (MHz)	Sensing Material	Sensitivity (Hz/ppm)	Response and Recovery times	Ref.			
200	SiO <sub>2</sub> /TiO <sub>2</sub>	2000	75 s and 140 s (in 40 ppm)	[30]			
200	$SiO_2/SnO_2$	210	220 s and 240 s (in 40 ppm)	[31]			
200	TiO <sub>2</sub>	500	45 s and 125 s (in 50 ppm)	[32]			
200	ZnO/SiO <sub>2</sub>	113.2	80 s and 80 s (in 50 ppm)	[33]			
200	ZnS	190	40 s and 80 s (in 20 ppm)	[34]			
123	MoS <sub>2</sub> /SiO <sub>2</sub>	1932	21 s and 23 s (in 50 ppm)	Present work			

Table 2SAW ammonia sensor performance

# 4. Conclusions

In this study, we successfully prepared a delay line SAW element with a center frequency of approximately 123 MHz using a 128° Y-cut LiNbO<sub>3</sub> piezoelectric substrate. The sensing materials of pure MoS<sub>2</sub> and composites with the MoS<sub>2</sub>–SiO<sub>2</sub> (M–S) structure and the SiO<sub>2</sub>–MoS<sub>2</sub> (S–M) structure were sprayed on the delay line areas of the SAW devices as the NH<sub>3</sub> gas sensors.

By adjusting the amount of catalyst NH<sub>4</sub>OH in the precursors, the particle sizes of SiO<sub>2</sub> nanospheres were successfully controlled at 70, 200, and 300 nm by the sol-gel method. Then, SiO<sub>2</sub> nanospheres were added to the precursor to prepare the rosette-shaped MoS<sub>2</sub>, and nanocomposites were synthesized by the hydrothermal method. Through EDS mapping of elemental analysis, we found that the MoS<sub>2</sub>–SiO<sub>2</sub> (M–S) structure can be synthesized using 300 nm SiO<sub>2</sub> nanospheres completely covered by MoS<sub>2</sub>. The SiO<sub>2</sub>–MoS<sub>2</sub> (S–M) structure can be synthesized using 70 nm SiO<sub>2</sub> nanospheres, which were distributed around MoS<sub>2</sub> flower spheres. Through the BET analysis, it was revealed that the composite material with the S–M structure had the highest specific surface area of 115.57 m<sup>2</sup>/g with optimized adsorption and desorption characteristics.

The SAW gas sensors fabricated using  $MoS_2$  and composite materials with the M–S and S–M structures were denoted as Sensor-A, Sensor-B, and Sensor-C, respectively. The sensitivities of Sensor-A, Sensor-B, and Sensor-C were determined to be 1643, 1849, and 1932 Hz/ppm, respectively. All three sensors have good selectivity; however, Sensor-C had a lower selectivity than Sensor-A and Sensor-B. The reason may be that the (–OH) hydroxyl group in SiO<sub>2</sub> will form hydrogen bonds not only with NH<sub>3</sub>, but also with acetone and alcohol. By the dynamic response measurement, it was found that the response times were 32, 30, and 21 s, for Sensor-A, Sensor-B, and Sensor-C, whereas the recovery times were 35, 33, and 23 s, respectively. A sensing linearity with an R-squared value of about 0.99167 was obtained for Sensor-C through continuous dynamic sensing with ammonia gas concentrations of 5–50 ppm. Finally, in this study, we discovered that composite materials with special M–S and S–M structures were synthesized from SiO<sub>2</sub> with different particle sizes and successfully revealed that modifying  $MoS_2$  with SiO<sub>2</sub> nanospheres improved the adsorption of ammonia molecules and significantly increased the sensitivity of the sensor.

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